

# Neighborhood semantics for deontic and agency logics

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# Non-ideal systems

- In complex systems we may not have full control over the behaviour of all its components:
  - incomplete information,
  - “black box” components,
  - it’s too expensive or complex to do so,
  - humans are involved,...
- Thus, *failure* may occur and the system must be prepared to react to that.
- Non-ideality has to be taken as a natural ingredient, from first stages of development.
- Instead of describing how the system *will behave* we can only say how the system *should behave*:
  - **it is necessary** is replaced by **it is obligatory**,
  - **it is possible** is replaced by **it is permitted**.

# Non-ideal systems

- Contract-based (normative) specification :
  - specify what is the obligatory and permitted behaviour (norms),
  - assume that components may deviate from that ideal behaviour (violate norms),
  - define what to do when violations to expected behaviour occur (sanctions, recovery procedures)
- Norms: represented by the set of obligations and permissions that result from them.
- Our aim: contribute with a high-level model and a logic to reason about it.

# Non-ideal systems

## Relevant concepts:

- We want to be able to speak about *obligations* and *permissions*.
- We are interested in: *obligation (and permission) to do* (as opposed to *obligation to be*).
- Obligations are fulfilled by agents through actions:  
“Agent  $x$  is obliged to pay the debt” meaning “It is obligatory that agent  $x$  pays the debt”.
- So, we need an *agency* concept.
- We also need to relate *obligations* with *actions of agents*.

# Non-ideal systems

As failure may occur, it is important to confront *expected behavior* (obligations, permissions, ...) with *actual behaviour* (actions of agents), detect *violations* of obligations (forbidden actions or not permitted actions) and identify *agents responsible for them*.

We will use deontic and agency logics.

# Deontic Logic

Deontic modal language  $\mathcal{L}_D(At)$  ( $At$  set of atomic propositions)

$\psi ::= p \mid \neg\psi \mid \psi \rightarrow \psi \mid O\psi \quad p \in At$

$\wedge, \vee, \leftrightarrow$  defined as usual.

$P\psi \stackrel{\text{def}}{=} \neg O\neg\psi.$

$O\phi$  : “it is obligatory that  $\phi$ ”

- $O$ : states what is obligatory to do, what ought to be done.
- $P$ : states what is permitted.

# SDL-Standard Deontic Logic

## Axiomatics

PC Any axiomatization of proposition logic.

(K)  $O(\psi \rightarrow \phi) \rightarrow (O\psi \rightarrow O\phi)$

(D)  $O\psi \rightarrow \neg O\neg\psi$

(MP)  $\frac{\psi \quad \psi \rightarrow \phi}{\phi}$

(Nec)  $\frac{\psi}{O\psi}$

Axiom (D) tells that “what is obligatory is permitted” or, equivalently, that “there cannot exist conflicts of obligations”:  
(D)  $\neg(O\psi \wedge O\neg\psi)$ .

SDL is a *KD* normal modal logic.



# SDL: Paradoxes

SDL leads to well known paradoxes :Ross paradox, Chisholm paradox, gentle murder paradox,...

Questions raised by the “paradox of gentle murder” are relevant to our context.

# SDL: Paradox of gentle murder

Statements:

- (1) Jones murders Smith.
- (2) Jones ought not to murder Smith.
- (3) If Jones murders Smith, then Jones ought to murder Smith gently.

Another fact:

- (4) If Jones murders Smith gently, then Jones murders Smith.

From (4) and (RM) rule we can infer:

- (5) If Jones ought to murder Smith gently, then Jones ought to murder Smith.

From (1) and (3) we have:

- (6) Jones ought to murder Smith gently.

And from (5) and (6) we infer

- (7) Jones ought to murder Smith.

which contradicts (2).

# SDL: Paradoxes

## *Monotonicity*

is the main cause for this paradox. We will need *weaker logics than  $K$*  in order to avoid undesirable inferences of this kind.

Other paradoxes are related with different problems: the representation of contrary to duties or conditional obligations, for instance.

# Deontic logic

The deontic logic we use:

## Axiomatics

(PC) Any axiomatization of proposition logic.

(D)  $O\psi \rightarrow \neg O\neg\psi$

(MP) 
$$\frac{\psi \quad \psi \rightarrow \phi}{\phi}$$

(RE) 
$$\frac{\psi \leftrightarrow \phi}{O\psi \leftrightarrow O\phi}$$

This is a non-normal ED modal logic.

# Deontic Logic

The semantic we adopt:

## Semantics: neighbourhood deontic models

A neighborhood deontic frame  $F$  is a pair  $F = \langle W, N_o \rangle$  where  $W$  is a non-empty set of worlds and  $N_o$  is a neighborhood deontic function  $N_o : W \longrightarrow \mathcal{P}(\mathcal{P}(W))$ . A model based on  $F$  is a tuple  $\langle W, N_o, V \rangle$  where  $V$  is a valuation function  $V : W \longrightarrow \mathcal{P}(At)$ .

$N_o(w)$  assigns to each world the set of propositions obligatory in it. Propositions are represented by its truth set:

$$\| \psi \|_M = \{w \mid M, w \Vdash \psi\}$$

# Deontic Logic

## Validity of formulas in a model:

- $M, w \Vdash p$  iff  $p \in V(w)$
- $M, w \Vdash \neg\psi$  iff  $M, w \not\Vdash \psi$
- $M, w \Vdash \psi \rightarrow \phi$  iff  $M, w \not\Vdash \psi$  or  $M, w \Vdash \phi$
- $M, w \Vdash O\psi$  iff  $\|\psi\|_{M \in N_o(w)}$

## $F \Vdash \psi$

A frame  $F$  validates a formula  $\psi$  if all models based on  $F$  validate  $\psi$ .

# Deontic Logic

Some known results:

## Properties of neighborhood deontic frames

Let  $F = \langle W, N_o \rangle$  be a neighborhood deontic frame. The axiom (D) defines a *proper frame*, i.e.,  $F \models O\psi \rightarrow \neg O\neg\psi$  iff for all  $w$ , if  $X \in N_o(w)$  then  $(W - X) \notin N_o(w)$ .

# Agency Logic

Agency modal language  $\mathcal{L}_A(At)$  ( $At$  set of atomic propositions)

$\psi ::= p \mid \neg\psi \mid \psi \rightarrow \psi \mid \{E_a\psi\}_{a \in Ag}$  where  $Ag$  is a set of agents and  $p \in At$

$\wedge, \vee, \leftrightarrow$  defined as usual.

$E_i \phi$  : “agent  $i$  brings about  $\phi$ ”

$E_i \phi$  relates the **agent** (actor, component, ...)  $i$  with the **state of affairs**  $\phi$  he brings about, abstracting from the *concrete actions* done to obtain that *state of affairs* and putting aside temporal issues.



# Agency logic

## Axiomatics

PC Any axiomatization of proposition logic.

$$(T) \quad E_i\psi \rightarrow \psi$$

$$(C) \quad E_i\psi \wedge E_i\phi \rightarrow E_i(\psi \wedge \phi)$$

$$(MP) \quad \frac{\psi \quad \psi \rightarrow \phi}{\phi}$$

$$(RE) \quad \frac{\psi \leftrightarrow \phi}{E_i\psi \leftrightarrow E_i\phi}$$

This is a non-normal ETC modal logic.

# Agency Logic

## Semantics: neighbourhood agency models

A neighborhood agency frame  $F$  is a pair  $F = \langle W, \{N_{e_i}\}_{i \in Ag} \rangle$  where  $W$  is a non-empty set of worlds and  $N_{e_i}$  is a neighborhood agency function  $N_{e_i} : W \rightarrow \mathcal{P}(\mathcal{P}(W))$ . A model based on  $F$  is a tuple  $\langle W, \{N_{e_i}\}_{i \in Ag}, V \rangle$  where  $V$  is a valuation function  $V : W \rightarrow \mathcal{P}(At)$ .

$N_{e_i}(w)$  assigns to the world  $w$  the set of propositions the agent  $i$  brings about in  $w$ .

## Validity of formulas in a neighborhood agency model:

- $M, w \models p$  iff  $p \in V(w)$
- $M, w \models \neg\psi$  iff  $M, w \not\models \psi$
- $M, w \models \psi \rightarrow \phi$  iff  $M, w \not\models \psi$  or  $M, w \models \phi$
- $M, w \models E_i\psi$  iff  $\|\psi\|_M \in N_{e_i}(w)$

# Agency Logic

Some known results:

## Properties of neighborhood agency frames

Let  $F = \langle W, N_{e_i} \rangle$  be a neighborhood agency frame.

- $F \models E_i \psi \wedge E_i \phi \rightarrow E_i(\psi \wedge \phi)$  iff  $F$  is *closed under finite intersections* (i.e., if for any collection of sets  $\{X_i\}_{i \in I}$  ( $I$  finite), for each  $i \in I$ ,  $X_i \in N_{e_i}(w)$ , then  $(\bigcap_{i \in I} X_i) \in N_{e_i}(w)$ ).
- $F \models E_i \psi \rightarrow \psi$  iff for each  $w \in W$ ,  $N_{e_i}(w) \neq \emptyset$  and  $w \in \bigcap N_{e_i}(w)$

# Deontic and Agency Logic

Deontic and agency modal language  $\mathcal{L}_{DA}(At)$  ( $At$  set of atomic propositions)

$\psi ::= p \mid \neg\psi \mid \psi \rightarrow \psi \mid O\psi \mid \{E_a\psi\}_{a \in Ag}$  where  $Ag$  is a set of agents and  $p \in At$

$\wedge, \vee, \leftrightarrow$  defined as usual,  $P$  defined as above.

# Deontic and Agency Logic

## Logical properties:

PC Any axiomatization of proposition logic.

$$(MP) \frac{\psi \quad \psi \rightarrow \phi}{\phi}$$

$$(Te) E_i\psi \rightarrow \neg\psi$$

$$(Ce) E_i\psi \wedge E_i\phi \rightarrow E_i(\psi \wedge \phi)$$

$$(REe) \frac{\psi \leftrightarrow \phi}{E_i\psi \leftrightarrow E_i\phi}$$

$$(Do) O\psi \rightarrow \neg O\neg\psi$$

$$(REo) \frac{\psi \leftrightarrow \phi}{O\psi \leftrightarrow O\phi}$$

$$(Coe) OE_i\psi \wedge OE_i\phi \rightarrow OE_i(\psi \wedge \phi)$$

$$(Cop) OE_i\psi \wedge PE_i\phi \rightarrow PE_i(\psi \wedge \phi)$$

$$(RMep) \frac{E_i\psi \rightarrow E_k\phi}{PE_i\psi \rightarrow PE_k\phi}$$

# Deontic and Agency Logic

Neighborhood deontic and agency models:

$M = \langle W, N_o, \{N_{e_i}\}_{i \in Ag}, V \rangle$  where:

- $N_o : W \longrightarrow \mathcal{P}(\mathcal{P}(W))$
- $N_{e_i} : W \longrightarrow \mathcal{P}(\mathcal{P}(W))$
- $V : W \longrightarrow \mathcal{P}(At)$

# Deontic and Agency Logic

We can reformulate a neighborhood function as follows:

$$f_{\Box} : \mathcal{P}(W) \longrightarrow \mathcal{P}(W)$$

$$w \in f_{\Box}(X) \text{ iff } X \in N_{\Box}(w)$$

$f_{\Box}(X)$  gives the set of worlds where  $X$  is necessary.

Thus:

- $f_{e_i}(X)$  gives the set of worlds where the agent  $i$  brings about (the proposition)  $X$ .
- $f_{\circ}(X)$  gives the set of worlds where (the proposition)  $X$  is obligatory.

Now we have:  $\| \Box \psi \| = f_{\Box}(\| \psi \|)$  which facilitates the expression of the semantics of iterated modal operators (as composition of neighborhood functions).

- $\| \top \| = W$
- $\| \perp \| = \emptyset$
- $\| \neg \psi \| = W - \| \psi \|$
- $\| \psi \wedge \phi \| = \| \psi \| \cap \| \phi \|$
- $\| \psi \vee \phi \| = \| \psi \| \cup \| \phi \|$
- $\| \psi \rightarrow \phi \| = \| \psi \| \subseteq \| \phi \|$
- $\| E_i \psi \| = f_{e_i}(\| \psi \|)$
- $\| O\psi \| = f_o(\| \psi \|)$



Using this function, the semantic characterization of formulas is “closest” to the syntactic form of formulas.

### Logical Formulas vs. Semantic Properties:

$$\text{Te } f_{ei}(X) \subseteq X$$

$$\text{Ce } f_{ei}(X) \cap f_{ei}(Y) \subseteq f_{ei}(X \cap Y)$$

$$\text{Do } f_o(X) \cap f_o(W - X) = \emptyset$$

$$\text{Coe } f_o(f_{ei}(X)) \cap f_o(f_{ei}(Y)) \subseteq f_o(f_{ei}(X \cap Y))$$

$$\text{Cop } (f_o(f_{ei}(X)) - f_o(W - f_{ei}(Y))) \cap f_o(W - f_{ei}(X \cap Y)) = \emptyset$$

$$\begin{aligned} \text{RMep } & \text{if } f_{ei}(X) \subseteq f_{ek}(Y) \text{ then} \\ & f_o(W - f_{ek}(Y)) \subseteq f_o(W - f_{ei}(X)) \end{aligned}$$

# Analysis supported

## Expressivity

- $OE_i\psi$  (obligatory actions)
- $PE_i\psi$  (permitted actions)
- $E_iE_k\psi$  (control)
- $E_iOE_k\psi$  (command)
- $E_iPE_k\psi$  (authorisation)
- ...

We will restrict our attention here to the first two formula schemas.

## Personal deontic operators

- $O_i\phi \stackrel{abv}{=} OE_i\phi$
- $P_i\phi \stackrel{abv}{=} PE_i\phi$

# Analysis supported

- Verify if an action is permitted:  $E_i\psi \wedge P_i\psi$
- Detect norm violations:
  - $O_i\psi \wedge E_i\neg\psi$
  - $\neg P_i\psi \wedge E_i\psi$
- Detect the fulfillment of some obligation:  $O_i\psi \wedge E_i\psi$
- Recovery or sanctioning of agents involved (effects of actions):
  - $(O_i\psi \wedge E_i\neg\psi) \rightarrow O_i\phi$
  - $(O_i\psi \wedge E_i\neg\psi) \rightarrow \neg P_i\phi$
- Other effects:
  - representation:  $E_i\psi \rightarrow E_k\psi$
  - conventional acts (count as):  $E_i\psi \rightarrow E_i\phi$

# Adding Context

## Effects of an action depend on action context

- The same action done by the same agent may have different effects depending on the context where the action was done.
- Roles may capture context of action.
- Permissions and obligations depend on roles. An agent may have permission to do  $\psi$  when acting in a role and not have permission to do the same action when acting in a different role.

# Adding Context

## Effects of an action depend on action context

- The same action done by the same agent may have different effects depending on the context where the action was done.
- Roles may capture context of action.
- Permissions and obligations depend on roles. An agent may have permission to do  $\psi$  when acting in a role and not have permission to do the same action when acting in a different role.
- Action in a role:  $E_{i:r}\psi$ : “agent  $i$  playing role  $r$  brings about  $\psi$ ”.
- Distinction between roles and agents.

## Additional expressivity

- $O_{i:r}\psi \stackrel{abv}{=} OE_{i:r}\psi$
- $P_{i:r}\psi \stackrel{abv}{=} PE_{i:r}\psi$
- $P_{i:r1}\psi \wedge \neg P_{i:r2}\psi$  or (contradictory permissions)
- $O_{i:r1}\psi \wedge O_{i:r2}\neg\psi$  (conflicting obligations)

# Questions

- What about dynamics?
- Effects of actions are not instantaneous.
- What is the meaning of worlds and neighborhoods in specification?
- How to combine the logics?
- ...

# Future work

- Add dynamics.
- Explore the fact that a neighborhood frame is a coalgebra for the contravariant powerset functor composed with itself  $2^2$ .  
(c.f. work of Y. Venema, H. Hansen, C. Kupke, E. Pacuit)



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