Decidability and Expressiveness results for Nondeterministic Probabilistic Automata

Alexandra Silva

joint work with



Justin Hsu



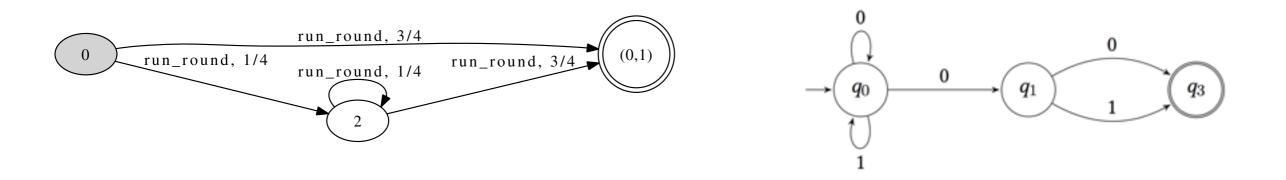
Gerco van Heerdt



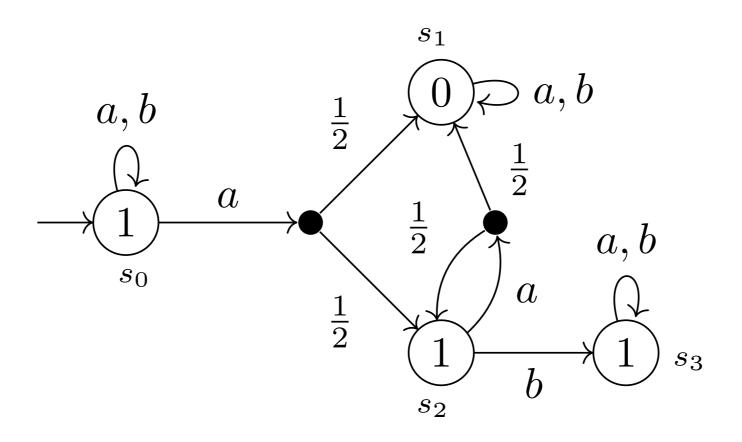
Joel Ouaknine

Context

- Probabilistic automata: randomized computation, semantics of programming languages, machine learning.
- Non-deterministic automata: concurrent and distributed systems
- Rabin 80's: use of nondeterminism and probabilities



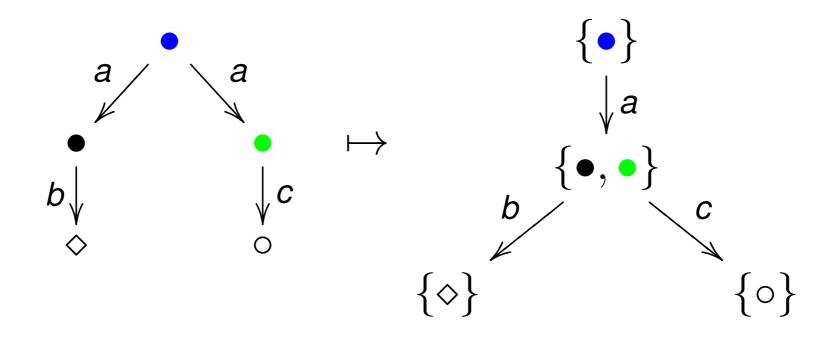
Non-deterministic probabilistic automata



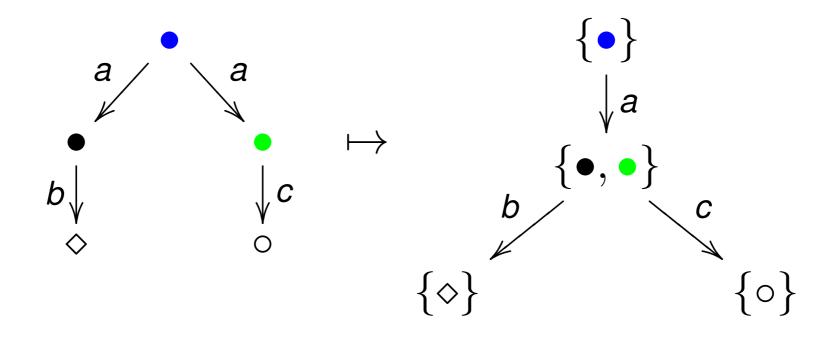
This talk

- Language semantics for NPA
- (Un)decidability
- Expressiveness of non-determinism

Language semantics via powerset construction



Language semantics via powerset construction



$$S
ightarrow \mathbf{2} imes \mathcal{P}(S)^{A}$$
 $\mathcal{P}(S)
ightarrow \mathbf{2} imes \mathcal{P}(S)^{A}$ $Q
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bisimilarity

language equivalence

$$S \xrightarrow{\langle o, t \rangle} 2 \times \mathcal{P}(S)^A$$



$$\mathcal{P}(S) \xrightarrow{\langle \bar{o}, \bar{t} \rangle} 2 \times \mathcal{P}(S)^A$$

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 $\bar{o}(U) = 1 \iff \exists u \in U.o(u) = 1$ $\bar{o}(U) = \bigvee_{U} o(u)$

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2 is a JSL

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 2 is a JSL

$$\mathcal{P}(S) \xrightarrow{\langle \bar{o}, \bar{t} \rangle} 2 \times \mathcal{P}(S)^A \qquad \bar{t}(U)(a) = \bigcup_U t(u)(a)$$

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JSL and P are closely related in a very general way

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P(S) is a JSL

JSL and P are closely related in a very general way

JSL are the algebras for the P monad

P is a monad

$$S \xrightarrow{} 2 \times \mathcal{P}(S)^A \qquad \bar{o}(U) = 1 \iff \exists u \in U.o(u) = 1$$

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We will used monads and algebras to define a generalised powerset construction and have a general language semantics for a class of automata

- Monads as effectful computation (Moggi 80's)
- Effects: non-determinism, probabilities, input-output, ...

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$$\mathcal{T}: Set \to Set$$

$$\eta\colon S\to \mathcal{T}S$$

$$\mu \colon \mathcal{T}\mathcal{T}S \to \mathcal{T}S$$

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- Effects: non-determinism, probabilities, input-output, ...

$$\mathcal{T}: Set \to Set$$

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$$\eta: S \to \mathcal{T}S$$

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- Monads as effectful computation (Moggi 80's)
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 μ,η satisfy some reasonable laws e.g. $\mu\circ\eta=id$

$$\mu \circ \eta = id$$

Associated with each monad there is a category of (free) algebras

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Definition An algebra for a monad (T, η, μ) is a pair (X, h) consisting of a carrier set X and a function $h: TX \to X$ making the following diagrams commute.

$$\begin{array}{c} X \xrightarrow{\eta} TX \\ \downarrow h \\ X \end{array}$$

$$TTX \xrightarrow{Th} TX$$

$$\downarrow \mu \qquad \qquad \downarrow h$$

$$TX \xrightarrow{h} X$$

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 ${\mathcal P}$ join-semilattices (with a bottom element)

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$$\downarrow \qquad \qquad \downarrow$$

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$$\alpha \colon \mathcal{T}(O) \to O$$

$$S \xrightarrow{\langle o, t \rangle} O \times \mathcal{T}(S)^A$$



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O is a T-algebra

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O is a T-algebra

T(S) is a T-algebra (free)

 $\bar{o}(s) = \alpha \circ (\mathcal{T}o)(s)$

$$S \xrightarrow{\langle o, t \rangle} [0, 1] \times \mathcal{D}(S)^{A}$$

$$\mathcal{D}(S) \xrightarrow{\langle \bar{o}, \bar{t} \rangle} [0, 1] \times \mathcal{D}(S)^A$$

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[0,1] is a convex algebra

m - monad multiplication

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Belief automaton

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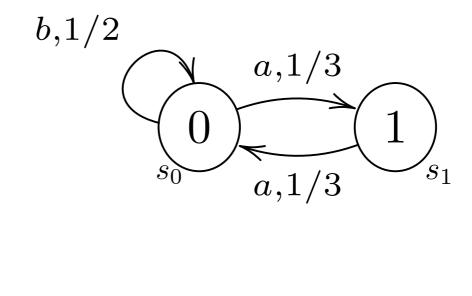
[0,1] is a convex algebra

m - monad multiplication

DPA, example

$$S \xrightarrow{\langle o, t \rangle} [0, 1] \times \mathcal{D}(S)^{A}$$

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DPA, example

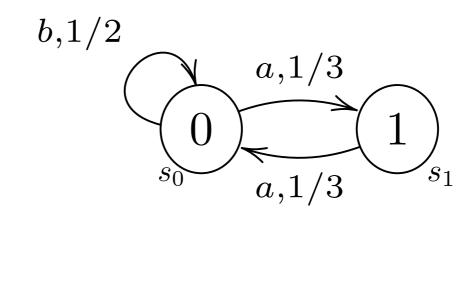
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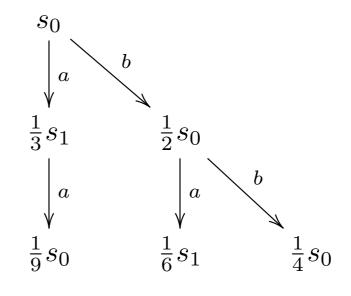
$$\mathcal{D}(S) \xrightarrow{\langle \bar{o}, \bar{t} \rangle} [0, 1] \times \mathcal{D}(S)^A$$

$$\mathcal{L}_s: A^* \to [0, 1]$$

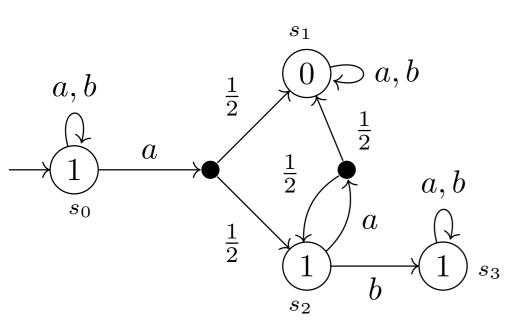
$$aa \mapsto \frac{1}{9} \times o(s_0) = \frac{1}{9} \times 0 = 0$$

$$ba \mapsto \frac{1}{6} \times o(s_1) = \frac{1}{6} \times 1 = \frac{1}{6}$$



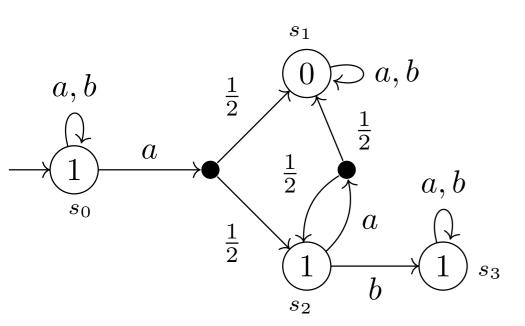


NPA



Definition A nondeterministic probabilistic automaton (NPA) over a (finite) alphabet A is defined by a tuple $(S, s_0, \gamma, \{\tau_a\}_{a \in A})$, where S is a finite set of states, $s_0 \in S$ is the initial state, $\gamma \colon S \to [0, 1]$ is the output function, and $\tau_a \colon S \to \mathcal{P}_c \mathcal{D}S$ are the transition functions indexed by inputs $a \in A$.

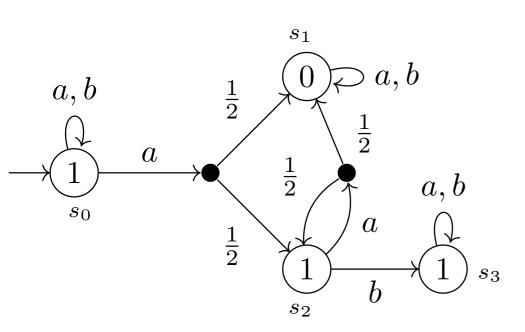
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$$S \rightarrow 2 \times \mathcal{P}(S)^{A}$$

NPA

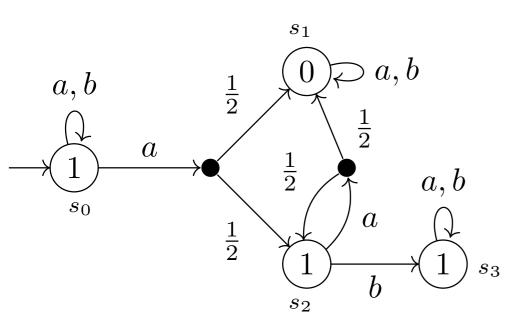


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$$S \to {\color{red} 2} imes {\color{blue} {\cal P}}(S)^{\color{red} {\sf A}}$$

$$S \to [0,1] \times \mathcal{P}_c \mathcal{D}(S)^A$$

NPA



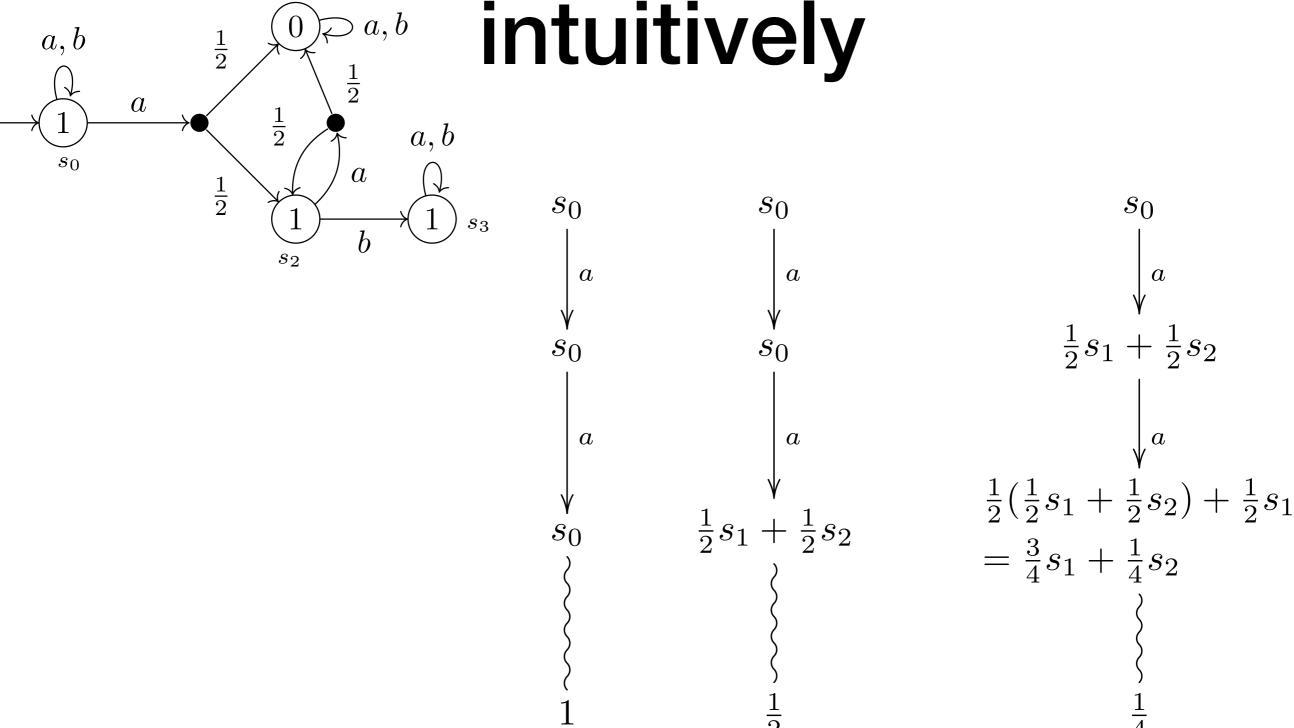
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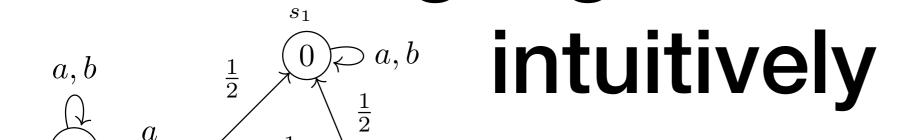
$$S o [0,1] imes \mathcal{P}_c \mathcal{D}(S)^A$$
 algebra monad

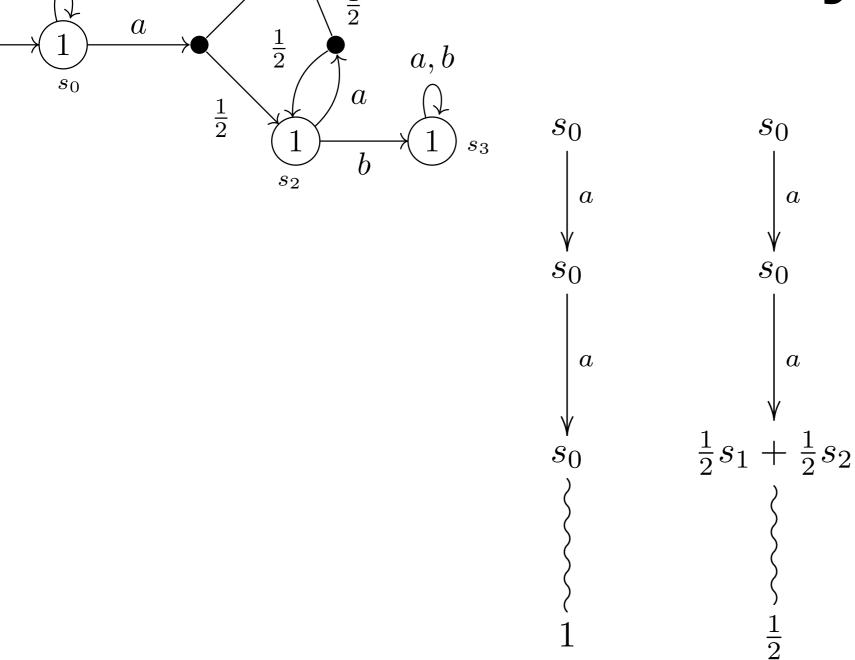
Language semantics

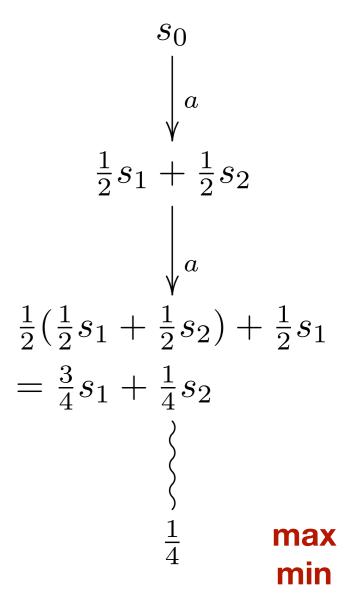


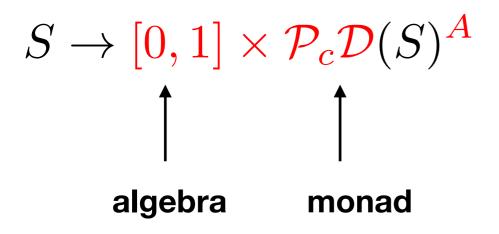


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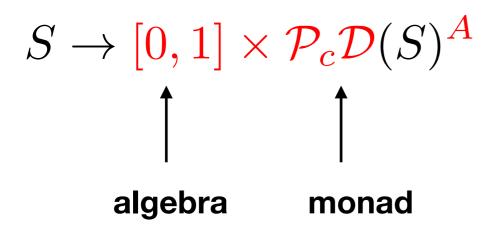






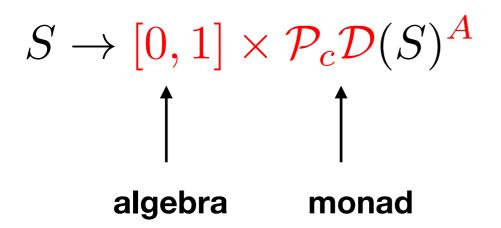


 $\mathcal{P}_c\mathcal{D}$ is a composite monad



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The semantics should be conservative set DPA



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The semantics should be conservative set DPA

$$\mathcal{D}[0,1]$$

$$\{-\} \downarrow \qquad \qquad \mathbb{E}$$

$$\mathcal{P}_c \mathcal{D}[0,1] \xrightarrow{o} [0,1]$$

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Proposition 1. Any $\mathcal{P}_c\mathcal{D}$ -algebra on [0,1] extending $\mathbb{E} \colon \mathcal{D}[0,1] \to [0,1]$ is of the form $\mathcal{P}_c\mathcal{D}[0,1] \xrightarrow{\mathcal{P}_c\mathbb{E}} \mathcal{P}_c[0,1] \xrightarrow{\alpha} [0,1]$, where α is a \mathcal{P}_c -algebra.

Proposition 2. The only \mathcal{P}_c -algebras on the convex set [0,1] are min and max.

Corollary 1. The only $\mathcal{P}_c\mathcal{D}$ -algebras on [0,1] extending \mathbb{E} are $\mathcal{P}_c\mathcal{D}[0,1] \xrightarrow{\mathcal{P}_c\mathbb{E}} \mathcal{P}_c[0,1] \xrightarrow{\text{max}} [0,1]$ and $\mathcal{P}_c\mathcal{D}[0,1] \xrightarrow{\mathcal{P}_c\mathbb{E}} \mathcal{P}_c[0,1] \xrightarrow{\text{max}} [0,1]$.

Proof:

Basic convex algebra facts

$$\begin{aligned} &\operatorname{\mathsf{Conv}}(\{\{0\},\{1\},[0,1]\}) \,=\, \operatorname{\mathcal{P}}_c[0,1] \\ &\operatorname{\mathcal{P}}_c[0,1] \stackrel{\alpha}{\longrightarrow} [0,1] \\ &\alpha \text{ is completely determined by } \alpha([0,1]) \\ &\alpha([0,1]) = 0 \text{ or } \alpha([0,1]) = 1 \end{aligned}$$

min or max

$$\mathcal{D}[0,1]$$

$$\{-\} \downarrow \qquad \qquad \mathbb{E}$$

$$\mathcal{P}_c \mathcal{D}[0,1] \xrightarrow{o} [0,1]$$

on [0,1] extending $\mathbb{E} \colon \mathcal{D}[0,1] \to [0,1]$ is of the

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min or max

$$\mathcal{D}[0,1]$$

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$$\mathcal{P}_c \mathcal{D}[0,1] \xrightarrow{o} [0,1]$$

on [0,1] extendi

form $\mathcal{P}_c\mathcal{D}[0,1] \xrightarrow{c} \mathcal{P}_c[0,1] \xrightarrow{\alpha} [0,1]$, where α is a

This formally explains why in the literature min and max are the only functions used

Proposition 2. The only \mathcal{P}_c -algebras on the convex set [0,1] are min and max.

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Summary, so far

$$S o [0,1] imes \mathcal{P}_c \mathcal{D}(S)^A$$
 $igg generalised powerset construction $egin{aligned} \mathcal{P}_c \mathcal{D}(S) o [0,1] imes \mathcal{P}_c \mathcal{D}(S)^A \end{aligned}$$

min and max are the only algebras

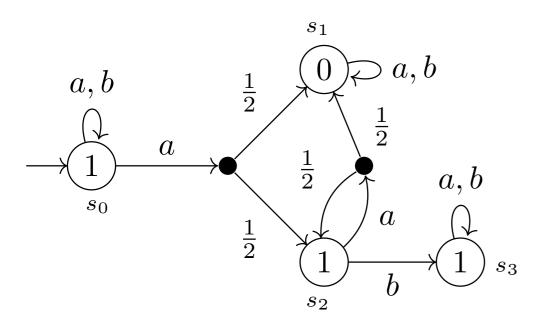
Deterministic automaton

Language semantics as usual using min/max to combine set of output results

Next

- Non-determinism brings a lot of trouble... is it necessary?
- Given two NPAs can we decide whether they are equivalent?

Is non-determinism really important?



$$\mathcal{L}_a: \{a,b\}^* \to [0,1] \text{ by } \mathcal{L}_a(u) = 2^{-n}$$

n - length longest sequence of a's in u

Theorem 1. NPAs are more expressive than DPAs. Specifically, there is no DPA, or even WFA, accepting \mathcal{L}_a .

Is non-determinism really important?

Theorem There is a language over a unary alphabet that is recognizable by an NPA but not by any WFA (and in particular any DPA).

Is non-determinism really important?

Theorem There is a language over a unary alphabet that is recognizable by an NPA but not by any WFA (and in particular any DPA).

Proof uses results of Linear recurrence sequences
Skolem-Macher-Lech Theorem
Cayley-Hamilton Theorem

Theorem Equivalence of NPAs is undecidable when $|A| \geq 2$ and the $\mathcal{P}_c\mathcal{D}$ -algebra on [0,1] extends the usual \mathcal{D} -algebra on [0,1].

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Proof. Let X be a DPA and $\kappa \in [0,1]$. We define NPAs Y and Z as follows:

$$Y = \bigcap_{\kappa} A \qquad \qquad Z = \longrightarrow (\kappa) A$$

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$$\mathcal{L}_Y(av) = (\alpha \circ \mathsf{Conv})(\{\kappa, \mathcal{L}_X(v)\}) \qquad \qquad \mathcal{L}_Z(av) = \kappa.$$

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$$\mathcal{L}_Y(\varepsilon) = \kappa = \mathcal{L}_Z(\varepsilon)$$

$$\mathcal{L}_Y(av) = (\alpha \circ \mathsf{Conv})(\{\kappa, \mathcal{L}_X(v)\}) \qquad \qquad \mathcal{L}_Z(av) = \kappa.$$

if $\alpha = \min$, then $\mathcal{L}_Y = \mathcal{L}_Z$ if and only if $\mathcal{L}_X(v) \geq \kappa$ for all $v \in A^*$

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Threshold problems undecidable for alphabets of size at least 2 [Blondel, Canterini'03]

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- (Un)decidability of threshold problem not know for |A|=1
- Reduction to the Positivity problem for LRS
- Decidability of Positivity open for >80 years
- Decision procedure would entail breakthroughs in open problems in number theory (algorithm to compute the homogeneous Diophantine approximation type for a class of transcendental numbers)

Corollary 2. The Positivity problem for linear recurrence sequences can be reduced to the equivalence problem of NPAs over a unary alphabet.

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Approximate the metric for any desired non-zero error:

Theorem There is a procedure that given $c \in [0,1)$, $\kappa > 0$, and computable functions $l_1, l_2 \colon A^* \to [0,1]$ outputs $x \in \mathbb{R}_+$ such that $|d_c(l_1, l_2) - x| \le \kappa$.

Conclusions

- Non-determinism + probabilities subtle from a semantics and algorithmic perspective
- Connections between and interplay of convex algebra, number theory, category theory
- Approximation techniques interesting for verification applications - different metrics?

Questions?