





### Coalgebraic learning

Alexandra Silva







# Automata learning

**Active learning** 

Passive learning

# Autonata carning

#### **Active learning**

Dana Angluin. Learning regular sets from queries and counterexamples. *Inf. Comput.*, 75(2):87–106, 1987.



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Dana Angluin. Learning regular sets L\* - algorithm

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Deterministic automata — only **simple** regular languages



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Deterministic automata — only **simple** regular languages

simple is beautiful.

## Autonata learning

#### **Active learning**

Dana Angluin. Learning regular sets

L\* - algorithm

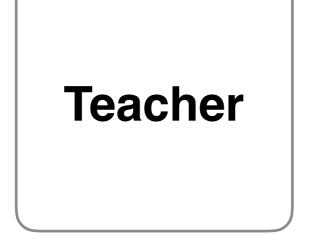
es. Inf. Comput., 75(2):87–106, 1987.

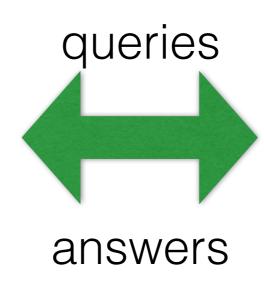
Deterministic automata — only **simple** regular languages

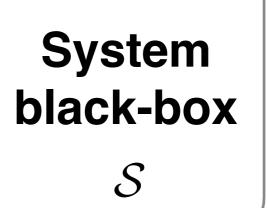
simple is beautiful.













automaton model of  $\mathcal{S}$ 

#### Teacher queries

Membership queries  $w \in \mathcal{L}$ ?

Equivalence queries  $\mathcal{L}(H) = \mathcal{L}$ ?

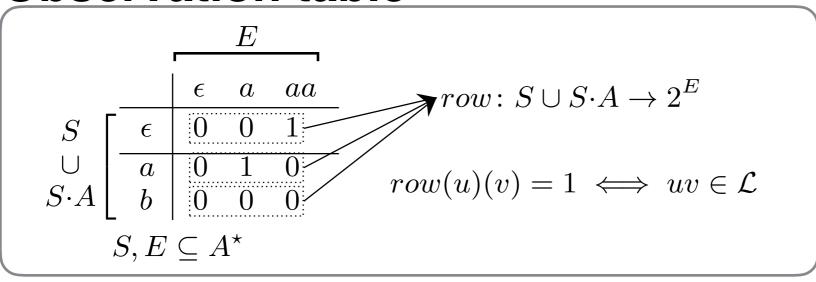
Yes :-) No :-( + counter-example

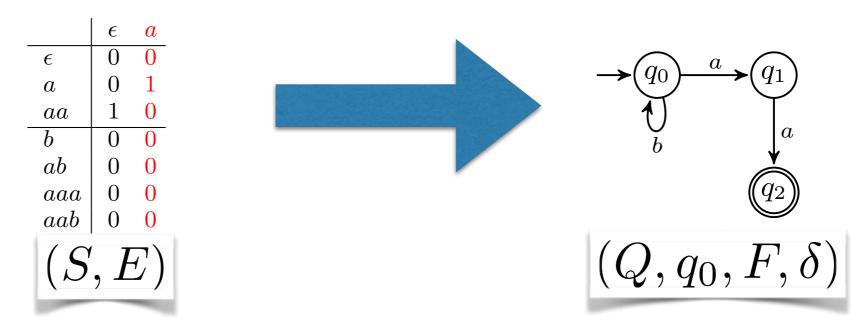
#### Teacher queries

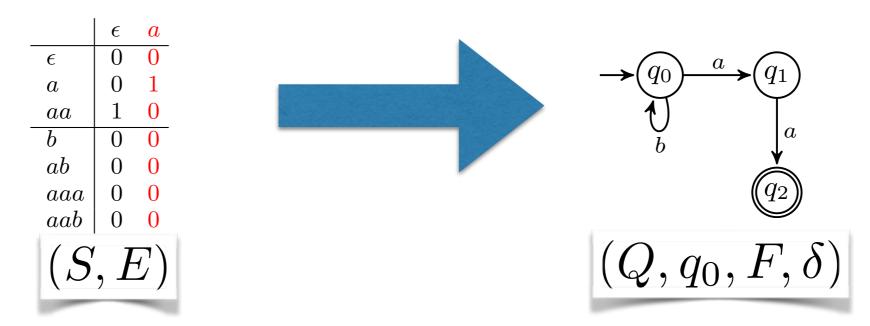
Membership queries 
$$w \in \mathcal{L}$$
?

Equivalence queries 
$$\mathcal{L}(H) = \mathcal{L}$$
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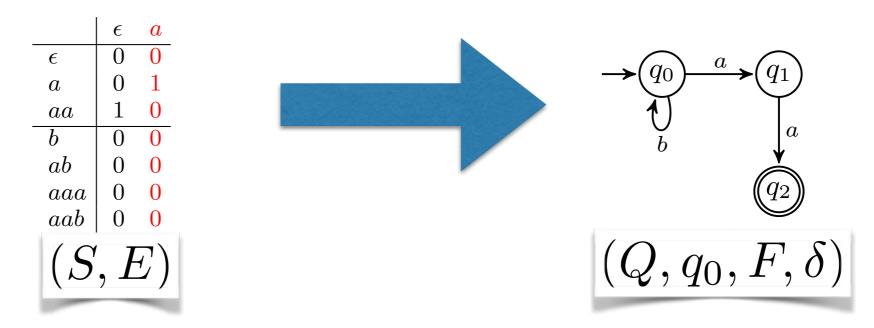
#### **Observation table**







- $Q = \{row(s) \mid s \in S\}$  is a finite set of states;
- $F = \{row(s) \mid s \in S, row(s)(\epsilon) = 1\} \subseteq Q$  is the set of final states;
- $q_0 = row(\epsilon)$  is the initial state;
- $\delta \colon Q \times A \to Q$  is the transition function given by  $\delta(row(s), a) = row(sa)$ .



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Why is this well-defined?

 $row: S \cup S \cdot A \rightarrow 2^E$ 

#### 

#### consistent

 $\forall s_1, s_2 \text{ s.t. } row(s_1) = row(s_2) \Rightarrow \forall a \in A \quad row(s_1a) = row(s_2a).$ 

 $row: S \cup S \cdot A \rightarrow 2^E$ 

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 $\delta(row(s), a) = row(sa)$  well-defined

 $row: S \cup S \cdot A \rightarrow 2^E$ 

# $\forall t \in S \cdot A \quad \exists s \in S \qquad row(t) = row(s).$

#### consistent

 $\forall s_1, s_2 \text{ s.t. } row(s_1) = row(s_1) \Rightarrow \forall a \in A \quad row(s_1a) = row(s_2a).$ 

row(sa) is a state

 $\delta(row(s), a) = row(sa)$  well-defined

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 $\forall s_1, s_2 \text{ s.t. } row(s_1) = row(s_2) \Rightarrow \forall a \in A \quad row(s_1a) = row(s_2a).$ 

choice of row(s) as representative is irrelevant  $\delta(row(s),a)=row(sa) \quad \text{well-defined}$ 

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$$\mathcal{L}_n = \{ ww \mid w \in A^*, |w| = n \}$$

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$$\begin{array}{c|c}
\hline
\epsilon & 0 \\
\hline
a & 0 \\
b & 0
\end{array}
\qquad \mathcal{A}_1 = \longrightarrow \boxed{q_0} \nearrow a/b$$

$$q_0 = row(\epsilon) = \{\epsilon \mapsto 0\}$$

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\begin{array}{c}
\mathcal{A}_1 = \longrightarrow \overline{q_0} \longrightarrow a/b \\
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$$egin{array}{c|cccc} \hline \epsilon & \hline e & \hline e & \hline e & \hline \end{array}$$
 $A_1 = \longrightarrow \overbrace{q_0} = a/b$ 
 $A_2 = -iccccc$ 
 $A_3 = -icccccc$ 
 $A_4 = -iccccc$ 
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 $A_6 = -icccc$ 
 $A_7 = -icccc$ 
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	$\epsilon$	4 (7)
$\epsilon$	0	$\mathcal{A}_1 = \longrightarrow q_0 \longrightarrow a/b$
$\overline{a}$	0	$q_0 = row(\epsilon) = \{\epsilon \mapsto 0\}$
b	$\begin{bmatrix} 0 \\ 0 \end{bmatrix}$	t - aa
	-	t = aa

$$egin{array}{c|c} \epsilon & \epsilon & 0 \ \hline a & 0 & 1 \ \hline a & 1 & 0 \ \hline a a & 1 & 0 \ a b & 0 \ a a a & 0 \ a a b & 0 \ \hline \end{array}$$

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$\overline{a}$	0
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$$A_1 = -Q_0$$
  $a/b$ 
 $q_0 = row(\epsilon) = \{\epsilon \mapsto 0\}$ 
 $t = aa$ 

$$egin{array}{c|cccc} \epsilon & \epsilon & 0 \ a & 0 & 1 \ \hline aa & 1 & 0 \ ab & 0 & aaa & 0 \ aab & 0 & 0 \ aab & 0 & 0 \ \end{array}$$

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$$\mathcal{L}_n = \{ ww \mid w \in A^*, |w| = n \}$$

$$\mathcal{L}_1 = \{ \bar{a}a, \bar{b}b \}$$

```
L* LEARNER
      S, E \leftarrow \{\epsilon\}
      repeat
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           while (S, E) is not closed or not consistent
           if (S, E) is not closed
  5
                 find s_1 \in S, a \in A such that
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                S \leftarrow S \cup \{s_1a\}
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           if (S, E) is not consistent
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	$\overline{\epsilon}$	$\frac{\epsilon}{0}$		$\mathcal{A}_1$ :	=	<b>→</b> (	$q_0$	$\supset a/b$
	$\overline{a}$	0	q	0 =	rou	$v(\epsilon)$ :	$= \{\epsilon$	$\mapsto 0$
	b	0		t	=	ac	$\iota$	
	$\epsilon$			$ \epsilon $	a			
	0	-	$\epsilon$	0	0			
	$0 \searrow$	a	a	0	1			
i	1	$\alpha$	aa	1	0			
	0	0	b	0	0			
)	0		ab	0	0			
$a \mid$	0		aaa	0	0			
$ab \mid$	0		aab	0	0			
	a	$egin{array}{c c} a & & & \\ \hline & & & \\ & & & \\ \hline $	$ \begin{array}{c cc} \hline \epsilon & 0 \\ \hline a & 0 \\ b & 0 \end{array} $ $ \begin{array}{c ccc} \hline  & 0 \\ \hline  & 0 \\ \hline  & 1 \\ \hline  & 0 \\ \hline  & $	$egin{array}{ c c c c c c c c c c c c c c c c c c c$	$egin{array}{ c c c c c c c c c c c c c c c c c c c$	$egin{array}{ c c c c c c c c c c c c c c c c c c c$	$egin{array}{ c c c c c } \hline \epsilon & 0 & A_1 = & \rightarrow (\epsilon) \\ \hline a & 0 & q_0 = row(\epsilon) = \\ b & 0 & t = a\epsilon \\ \hline & 0 & \hline \epsilon & a \\ \hline & 0 & a & 0 & 1 \\ \hline & 0 & a & 1 & 0 \\ \hline & 0 & ab & 0 & 0 \\ aa & 0 & aaa & 0 & 0 \\ \hline & aa & 0 & 0 & 0 \\ \hline & aa & 0 & 0 & 0 \\ \hline & aa & 0 & 0 & 0 \\ \hline & aa & 0 & 0 & 0 \\ \hline & aa & 0 & 0 & 0 \\ \hline & aa & 0 & 0 & 0 \\ \hline & aa & 0 & 0 & 0 \\ \hline & aa & 0 & 0 & 0 \\ \hline & aa & 0 & 0 & 0 \\ \hline & aa & 0 & 0 & 0 \\ \hline & aa & 0 & 0 & 0 \\ \hline & aaaa & 0 & 0 & 0 \\ \hline & aaaa & 0 & 0 & 0 \\ \hline & aaaa & 0 & 0 & 0 \\ \hline & aaaa & 0 & 0 & 0 \\ \hline & aaaa & 0 & 0 & 0 \\ \hline & aaaa & 0 & 0 & 0 \\ \hline & aaaa & 0 & 0 & 0 \\ \hline & aaaaa & 0 & 0 & 0 \\ \hline & aaaaa & 0 & 0 & 0 \\ \hline & aaaaa & 0 & 0 & 0 \\ \hline & aaaaa & 0 & 0 & 0 \\ \hline & aaaaa & 0 & 0 & 0 \\ \hline & aaaaa & 0 & 0 & 0 \\ \hline & aaaaa & 0 & 0 & 0 \\ \hline & aaaaa & 0 & 0 & 0 \\ \hline & aaaaa & 0 & 0 & 0 \\ \hline & aaaaaa & 0 & 0 & 0 \\ \hline & aaaaaa & 0 & 0 & 0 \\ \hline & aaaaaa & 0 & 0 & 0 \\ \hline & aaaaaa & 0 & 0 & 0 \\ \hline & aaaaaa & 0 & 0 & 0 \\ \hline & aaaaaaa & 0 & 0 & 0 \\ \hline & aaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaa$	$egin{array}{ c c c c c } \hline \epsilon & 0 & A_1 = & & & & & & & & & & & & & & & & & & $

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$$\mathcal{L}_1 = \{\bar{a}a, \bar{b}b\}$$

$$\mathcal{A}_2 = b \qquad q_1$$

$$q_1$$

$$q_2$$

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	$\epsilon$	U		$p(e) = \{\epsilon \mapsto 0\}$ $p(e) = \{a \mapsto 0\}$ $p(e) = \{a \mapsto 0\}$
$a = \begin{bmatrix} \epsilon \\ a \\ aa \end{bmatrix}$ $ab$ $aaa$ $aab$	$ \begin{array}{c c} \hline  & \\  & \\$	$egin{array}{c} \epsilon & a & \\ aa & \\ b & \\ ab & \\ aaa & \\ aab & \\ \end{array}$	$\begin{array}{cccc} \epsilon & a \\ \hline 0 & 0 \\ 0 & 1 \\ 1 & 0 \\ \hline 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ \end{array}$	

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L\* LEARNER

$$\mathcal{A}_2 = b \qquad q_1 \qquad q_1 \qquad q_2 \qquad q_2$$

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L\* LEARNER

$$\mathcal{A}_{2} = b$$

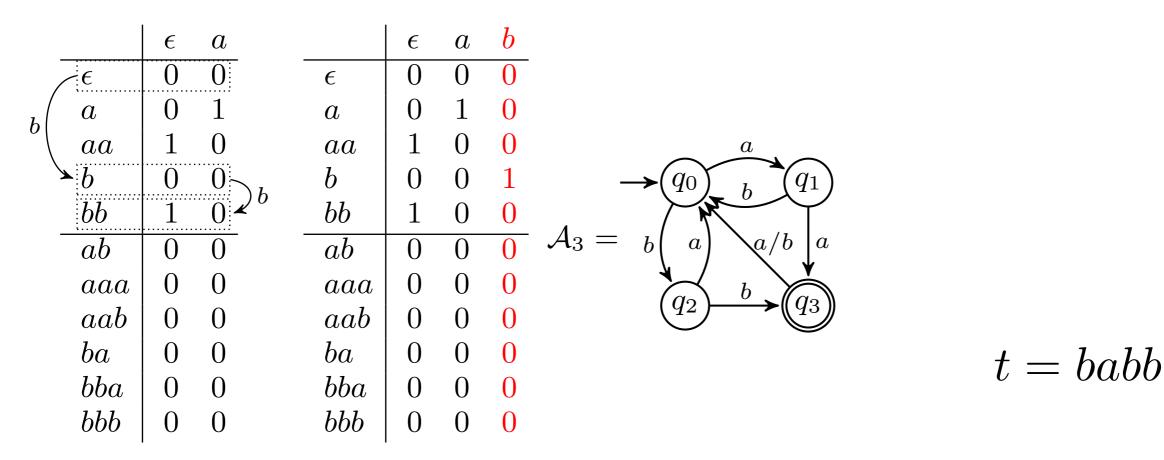
$$t = bb$$

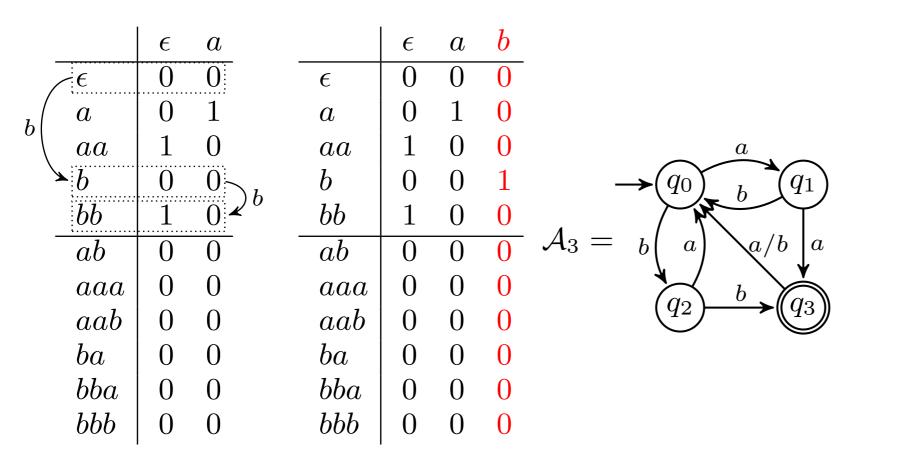
$$q_{0} \xrightarrow{a} q_{1}$$

$$\downarrow^{a}$$

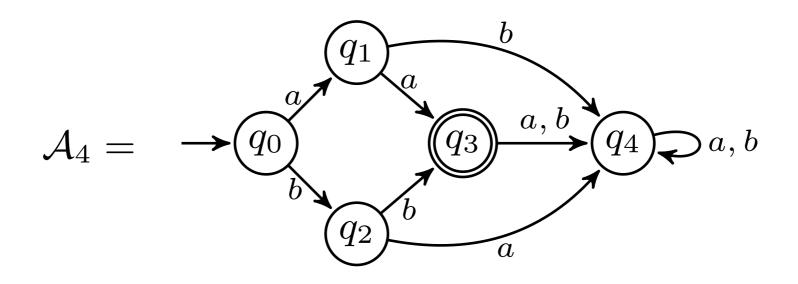
$$q_{2}$$

	$\epsilon$	a		$\epsilon$	a	b	
$\epsilon$	0	0	$\epsilon$	0	0	0	
b $a$	0	1	a	0	1	0	
aa	1	0	aa	1	0	0	a
<b>b</b>	0	$0 \searrow_{h}$	b	0	0	1	$\rightarrow (q_0) \begin{pmatrix} q_1 \end{pmatrix}$
bb	1	0 🗸 6	bb	1	0	0	
$\overline{ab}$	0	0	ab	0	0	0	$A_3 = b(a) a/b a$
aaa	0	0	aaa	0	0	0	b
aab	0	0	aab	0	0	0	$(q_2) \xrightarrow{0} (q_3)$
ba	0	0	ba	0	0	0	
bba	0	0	bba	0	0	0	
bbb	0	0	bbb	0	0	0	





t = babb



### Autonata learning

simple is beautiful.





Applications: Security, formal verification, ...

Generalisations: Mealy machines, I/O automata, ...

### Autonata learning

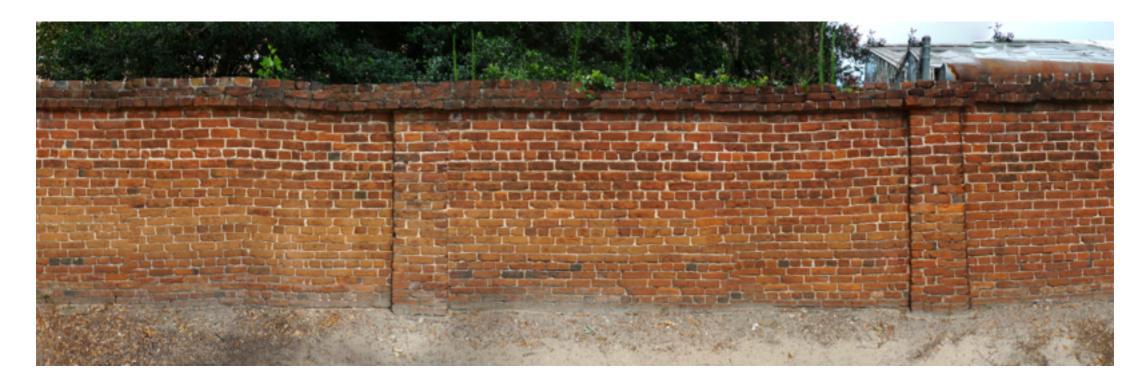
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### Autonata learning

simple is beautiful.





Applications: Security, formal verification, ...

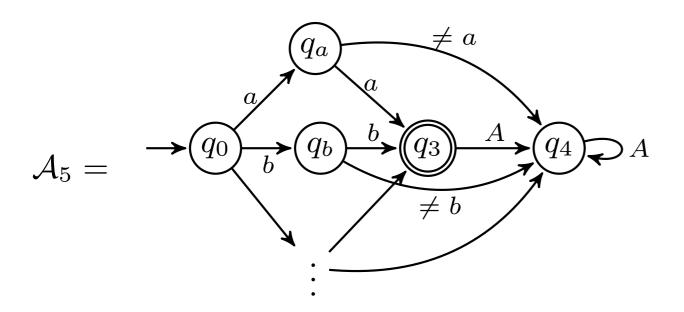
Generalisations: Mealy machines, I/O automata, ...



### Infinite alphabets

$$\mathcal{L}_n = \{ ww \mid w \in A^*, |w| = n \}$$

$$\mathcal{L}_1 = \{ \bar{a}a, \bar{b}b \}$$



infinite automaton

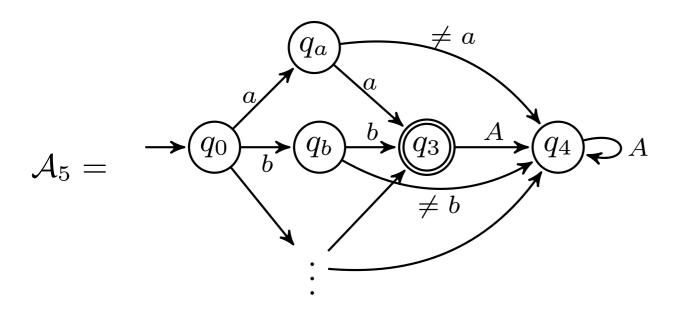
#### Infinite alphabets

$$\mathcal{L}_n = \{ ww \mid w \in A^*, |w| = n \}$$

 $\mathcal{L}_1 = \{aa, bb\}$ 

A infinite

$$\mathcal{L}_1 = \{aa, bb, cc, dd, \ldots\}$$



infinite automaton

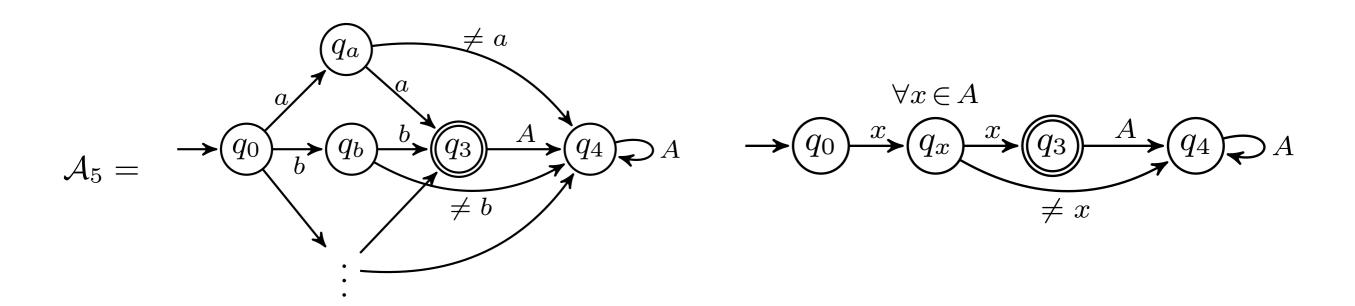
### Infinite alphabets

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A infinite

$$\mathcal{L}_1 = \{aa, bb, cc, dd, \ldots\}$$



infinite automaton

but with a finite representation







name binding alpha-equivalence

. . . . .







name binding alpha-equivalence

. . . . .

Infinite sets







name binding alpha-equivalence

. . . . .

Infinite sets with symmetries







name binding alpha-equivalence

Infinite sets with symmetries



Finitely representable







name binding alpha-equivalence

. . . . .



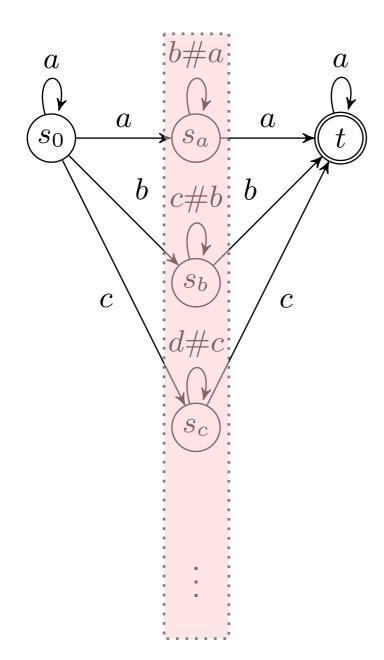




Automata theory over nominal sets

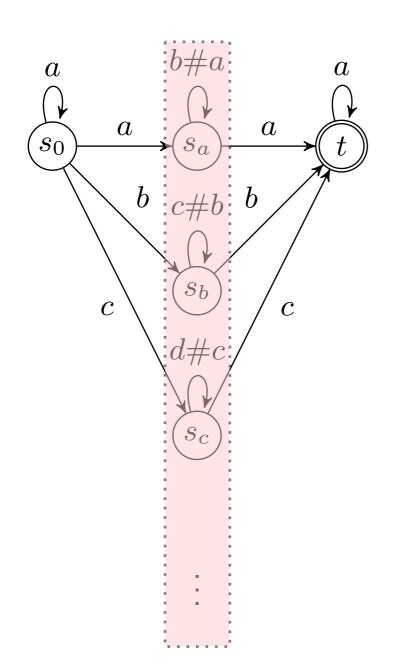
## Nomal automata.

A infinite



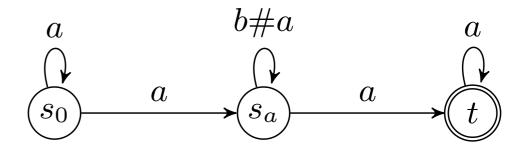
 $\{w \in \mathbb{A}^* \mid \exists a.a \text{ occurs twice in } w\}$ 

# Nomal attomata.



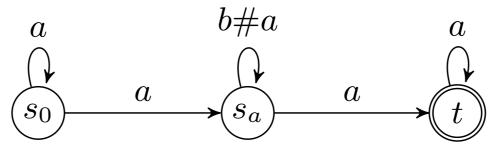
A infinite

 $\{w \in \mathbb{A}^* \mid \exists a.a \text{ occurs twice in } w\}$ 



finite representation

# Noma ettomata.



finite representation

canonical permutations

$$X = \{s_0\} + \mathbb{A} + \{t\}$$

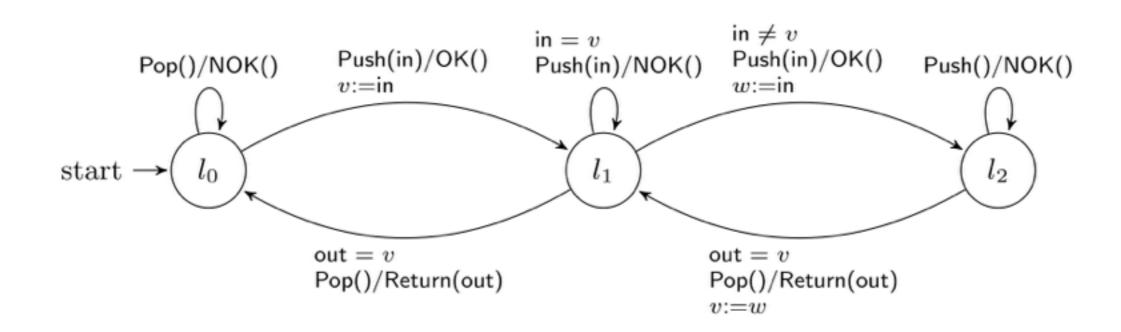
$$\pi: \mathbb{A} \to \mathbb{A}$$

$$s_a \mapsto s_{\pi a}$$

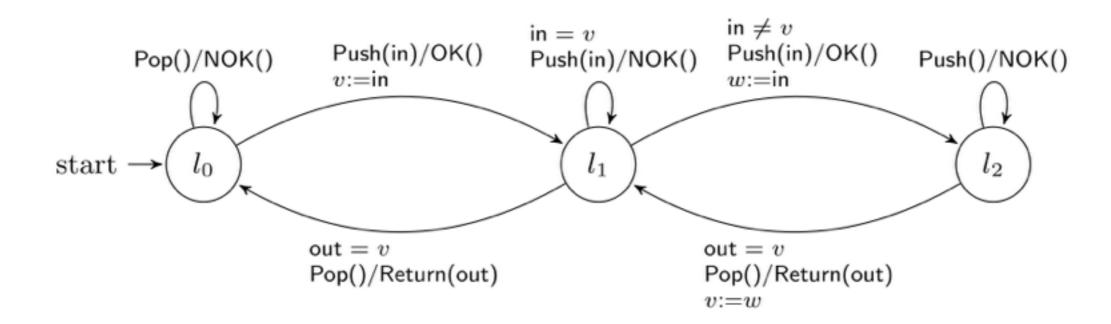
transition closed under permutations equivariant

$$s_a \xrightarrow{a} t \Rightarrow s_{\pi a} \xrightarrow{\pi a} t$$

## Nomal automata.

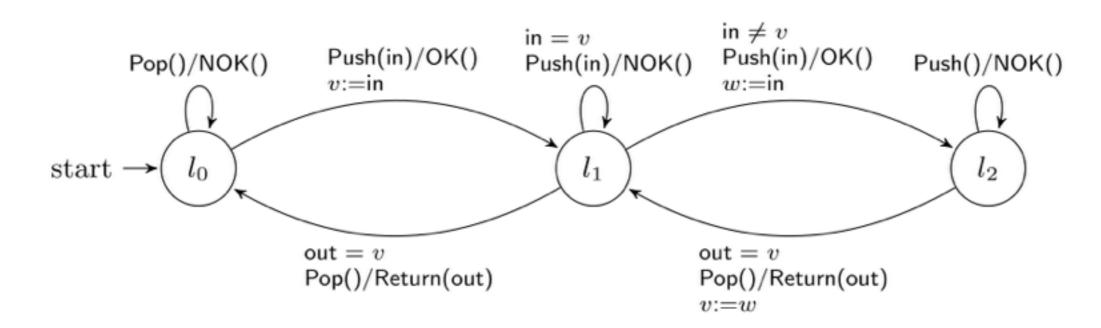


# Noma ettomata.



Better or worse than Nominal automata?

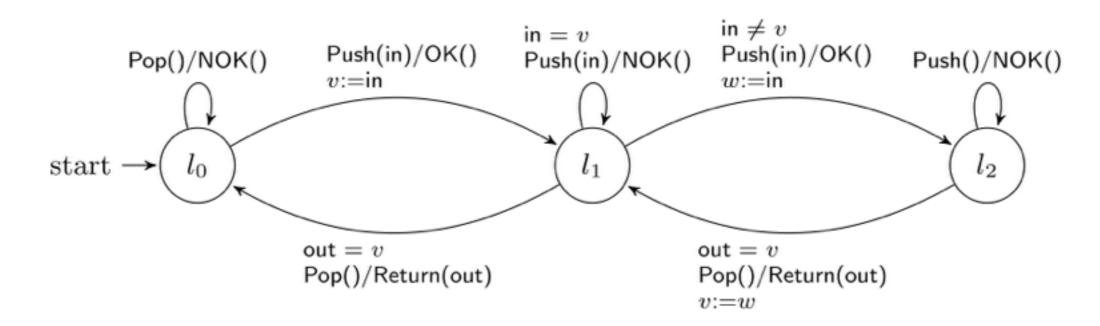
# Nomal attomata.



Better or worse than Nominal automata?

Nominal automata are just automata in Nom

## Nomal attomata.



Better or worse than Nominal automata?

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 $\lambda x. \mathbf{Nom}(x)$  research program

#### This talk

Learning algorithm for nominal automata

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Learning algorithm for nominal automata

using category theory & coalgebra

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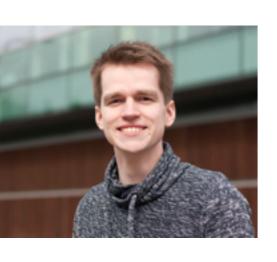
Angluin meets the Warsaw group

 $(\lambda x.\mathbf{Nom}(x))(L^*)$ 

#### Credits

Joshua Moerman, Matteo Sammartino, Alexandra Silva, Bartek Klin, Michal Szynwelski. Learning Nominal Automata.

Bart Jacobs, Alexandra Silva. **Automata Learning: A Categorical Perspective.** 











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           while (S, E) is not closed or not consistent
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range over infinite sets

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range over infinite sets

finding witnesses potentially requires checking infinite rows

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range over infinite sets

finding witnesses potentially requires checking infinite rows

t has only finitely many prefixes, but an infinite S is necessary

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     repeat
                                                                           range over infinite sets
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         while (S, E) is not closed or not consistent
         if (S, E) is not closed
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         if (S, E) is not consistent
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                                                                             t has only finitely many prefixes,
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no finite automaton accepts  $\mathcal{L}_1$ 

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                                                                              but an infinite S is necessary
     return M(S, E)
```

- **(P1)** the sets S, S·A and E admit a finite representation up to permutations;
- **(P2)** row is such that  $row(\pi(s))(\pi(e)) = row(s)(e)$ , for all  $s \in S$  and  $e \in E$ . Observation table admits a finite symbolic representation.

#### Nominal L\*

```
6' \qquad S \leftarrow S \cup \operatorname{orb}(sa)
9' \qquad E \leftarrow E \cup \operatorname{orb}(ae)
12' \qquad E \leftarrow E \cup \operatorname{prefixes}(\operatorname{orb}(t))
```

only 3 lines changed!

#### Nominal L\*

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only 3 lines changed!

not really... all definitions have to be adapted to nominal/equivariant.

### Nominal L\*

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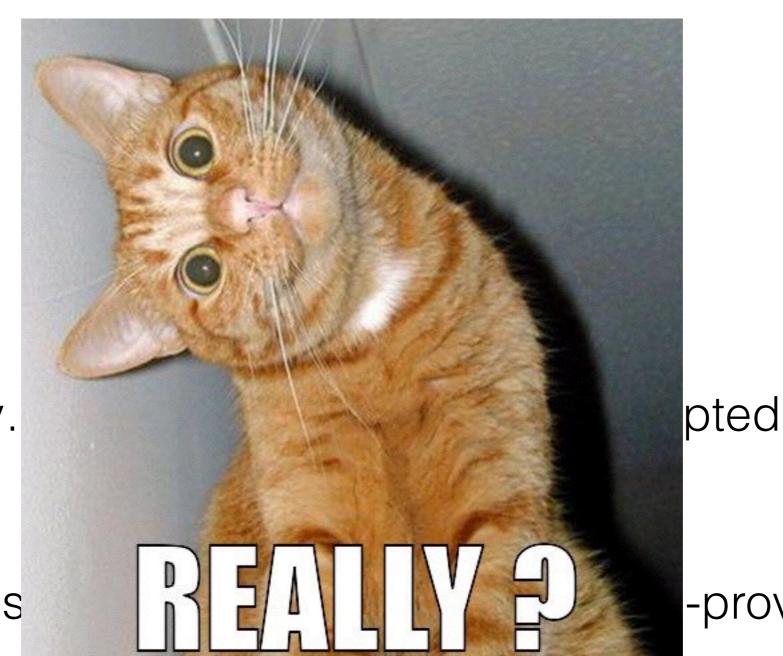
12' E \leftarrow E \cup \text{prefixes}(\text{orb}(t))
```

only 3 lines changed!

not really... all definitions have to be adapted to nominal/equivariant.

Correctness, termination, ... have to be re-proved!

### Nominal L\*

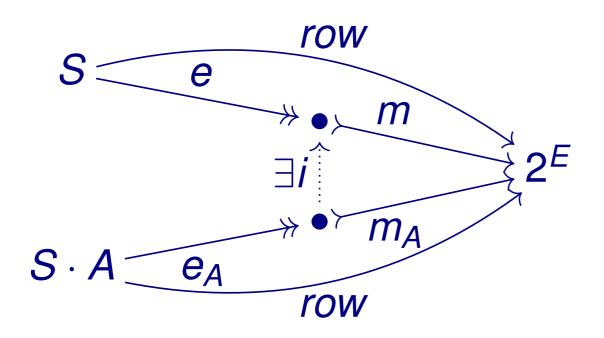


not really.

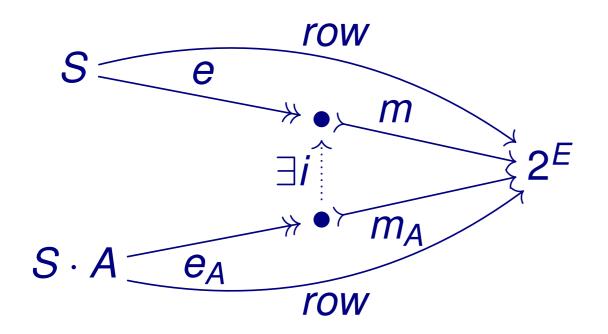
Correctnes

-proved!

(S, E, row) is *closed* if for all  $t \in S \cdot A$  there exists an  $s \in S$  such that row(t) = row(s).

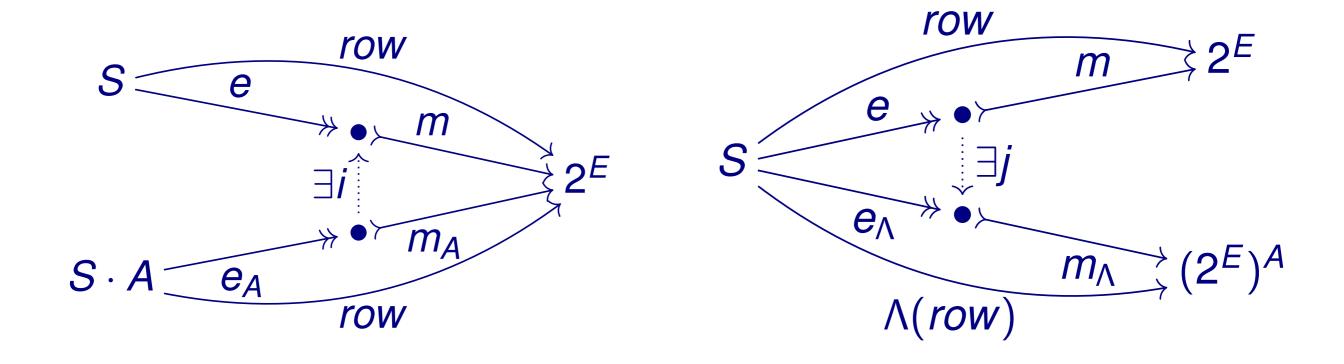


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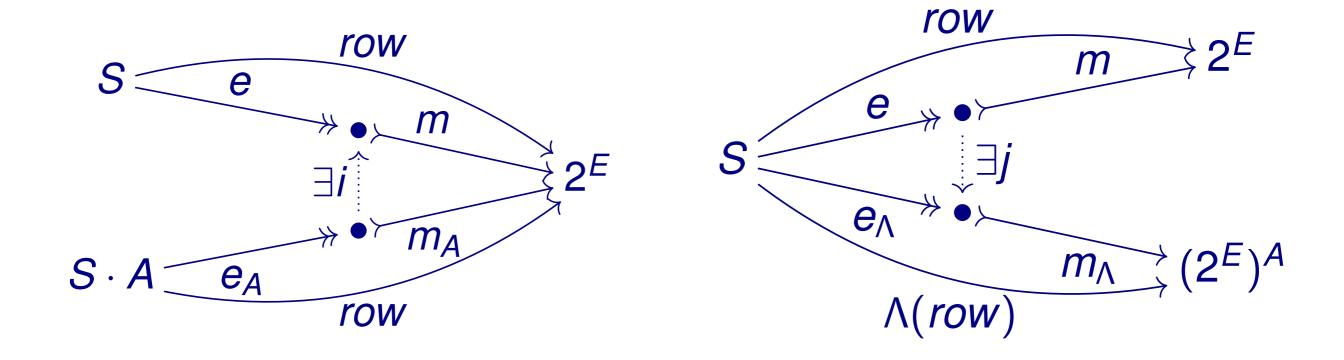
(S, E, row) is *closed* if for all  $t \in S \cdot A$  there exists an  $s \in S$  such that row(t) = row(s).

(S, E, row) is *consistent* if whenever  $s_1, s_2 \in S$  are such that  $row(s_1) = row(s_2)$ , for all  $a \in A$ ,  $row(s_1a) = row(s_2a)$ .



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(S, E, row) is closed if for all  $t \in S$  A there exists an  $s \in S$  such that Pretty.... but is it useful?

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## The power of abstraction

Definitions are the *same* 

Proof of correctness is the *same* 

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$$\begin{array}{c|c}
1 & init & final \\
A^* - - - - - \Rightarrow Q - - - - - \Rightarrow 2^{A*} \\
c & \delta & \partial \\
(A^*)^A - - - - \Rightarrow Q^A - - - - \Rightarrow (2^{A*})^A
\end{array}$$

## The power of abstraction

Learning weighted automata = vector spaces 2014, Jacobs&Silva

Learning NFAs = join semi lattices 2009, Bollig, Habermehl, Kern, Leucker - Angluin-style learning for NFA

Learning product automata = products Implicitly done by Rivest, Schapire (diversity based learning)

All of these only work for ordinary alphabets

Correctness was easy

Brings almost nothing new to the table

Easy to implement variations
For example, different counter example analysis

Works for any symmetry  $Aut(\mathcal{M})$  for any  $\omega$ -categorical model  $\mathcal{M}$  For example homogeneous structures:  $(\mathbb{N}, =)$ ,  $(\mathbb{Q}, \leq)$ ,  $(\mathcal{R}, adj)$ , ... Needed for products to be orbit-finite

Implementation was not easy
(Partly because the library for nominal computation was young)

Implementation is not efficient

No concrete communication with teacher yet (But theoretically possible)

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Abstraction is guidance but there is no free lunch!

### Future Work

Implementation

Succinctness

Other symmetries

Other tools

Verification

### Conclusions

simple is beautiful.

&

